

CONTENTS

Chapter 0 Introduction

1	Logic: quantifiers	1
2	The logical connectives	3
3	Negations of quantifiers	6
4	Sets	6
5	Restricted variables	8
6	Ordered pairs and relations	9
7	Functions and mappings	10
8	Product sets; index notation	12
9	Composition	14
10	Duality	15
11	The Boolean operations	17
12	Partitions and equivalence relations	19

Chapter I Vector Spaces

1	Fundamental notions	21
2	Vector spaces and geometry	36
3	Product spaces and $\text{Hom}(V, W)$	43
4	Affine subspaces and quotient spaces	52
5	Direct sums	56
6	Bilinearity	67

Chapter 2 Finite-Dimensional Vector Spaces

1	Bases	71
2	Dimension	77
3	The dual space	81
4	Matrices	88
5	Trace and determinant	99
6	Matrix computations	102
*7	The diagonalization of a quadratic form	111

Chapter 3 The Differential Calculus

1	Review in \mathbb{R}	117
2	Norms	121
3	Continuity	126

4	Equivalent norms	132
5	Infinitesimals	136
6	The differential	140
7	Directional derivatives; the mean-value theorem	146
8	The differential and product spaces	152
9	The differential and \mathbb{R}^n	156
10	Elementary applications	161
11	The implicit-function theorem	164
12	Submanifolds and Lagrange multipliers	172
*13	Functional dependence	175
*14	Uniform continuity and function-valued mappings	179
*15	The calculus of variations	182
*16	The second differential and the classification of critical points	186
*17	The Taylor formula	191
Chapter 4 Compactness and Completeness		
1	Metric spaces; open and closed sets	195
*2	Topology	201
3	Sequential convergence	202
4	Sequential compactness	205
5	Compactness and uniformity	210
6	Equicontinuity	215
7	Completeness	216
8	A first look at Banach algebras	223
9	The contraction mapping fixed-point theorem	228
10	The integral of a parametrized arc	236
11	The complex number system	240
*12	Weak methods	245
Chapter 5 Scalar Product Spaces		
1	Scalar products	248
2	Orthogonal projection	252
3	Self-adjoint transformations	257
4	Orthogonal transformations	262
5	Compact transformations	264

Chapter 6 Differential Equations		
1	The fundamental theorem	266
2	Differentiable dependence on parameters	274
3	The linear equation	276
4	The n th-order linear equation	281
5	Solving the inhomogeneous equation	288
6	The boundary-value problem	294
7	Fourier series	301
Chapter 7 Multilinear Functionals		
1	Bilinear functionals	305
2	Multilinear functionals	306
3	Permutations	308
4	The sign of a permutation	309
5	The subspace Ω^n of alternating tensors	310
6	The determinant	312
7	The exterior algebra	316
8	Exterior powers of scalar product spaces	319
9	The star operator	320
Chapter 8 Integration		
1	Introduction	321
2	Axioms	322
3	Rectangles and paved sets	324
4	The minimal theory	327
5	The minimal theory (continued)	328
6	Contented sets	331
7	When is a set contented?	333
8	Behavior under linear distortions	335
9	Axioms for integration	336
10	Integration of contented functions	338
11	The change of variables formula	342
12	Successive integration	346
13	Absolutely integrable functions	351
14	Problem set: The Fourier transform	355

Chapter 9	Differentiable Manifolds	
1	Atlasses	364
2	Functions, convergence	367
3	Differentiable manifolds	369
4	The tangent space	373
5	Flows and vector fields	376
6	Lie derivatives	384
7	Linear differential forms	390
8	Computations with coordinates	393
9	Riemann metrics	397
Chapter 10	The Integral Calculus on Manifolds	
1	Compactness	403
2	Partitions of unity	405
3	Densities	408
4	Volume density of a Riemann metric	411
5	Pullback and Lie derivatives of densities	416
6	The divergence theorem	419
7	More complicated domains	424
Chapter 11	Exterior Calculus	
1	Exterior differential forms	429
2	Oriented manifolds and the integration of exterior differential forms	433
3	The operator d	438
4	Stokes' theorem	442
5	Some illustrations of Stokes' theorem	449
6	The Lie derivative of a differential form	452
	Appendix I. "Vector analysis"	457
	Appendix II. Elementary differential geometry of surfaces in \mathbb{E}^3	459
Chapter 12	Potential Theory in \mathbb{E}^n	
1	Solid angle	474
2	Green's formulas	476
3	The maximum principle	477
4	Green's functions	479
Chapter 13	Classical Mechanics	
1	The tangent and cotangent bundles	511
2	Equations of variation	513
3	The fundamental linear differential form on $T^*(M)$	515
4	The fundamental exterior two-form on $T^*(M)$	517
5	Hamiltonian mechanics	520
6	The central-force problem	523
7	The two-body problem	528
8	Lagrange's equations	530
9	Variational principles	532
10	Geodesic coordinates	537
11	Euler's equations	541
12	Rigid-body motion	544
13	Small oscillations	551
14	Small oscillations (continued)	553
15	Canonical transformations	558
	Selected References	569
	Notation Index	572
	Index	575