
Table of Contents

Preface

PART I: Radar Principles

Chapter 1: Definitions and Nomenclature, 3

- 1.1. Radar Systems Classifications and Bands, 3
- 1.2. Pulsed and Continuous Wave (CW) Radars, 8
- 1.3. Range, 9
- 1.4. Range Resolution, 12
- 1.5. Doppler Frequency, 14
- 1.6. Coherence, 20
- 1.7. Decibel Arithmetic, 21
- Problems, 23
- Appendix 1-A: Chapter 1 MATLAB[®] Code Listings, 25
 - Function “*pulse_train.m*” Listing, 25
 - Function “*range_resolution.m*” Listing, 25
 - Function “*doppler_freq.m*” Listing, 26

Chapter 2: Basic Pulsed and Continuous Wave (CW) Radar Operations, 27

- 2.1. The Radar Range Equation, 27
- 2.2. Low PRF Radar Equation, 31
- 2.3. High PRF Radar Equation, 35
- 2.4. Surveillance Radar Equation, 37
- 2.5. Radar Equation with Jamming, 42
 - 2.5.1. Self-Screening Jammers (SSJ), 42
 - 2.5.2. Burn-Through Range, 44
 - 2.5.3. Stand-Off Jammers (SOJ), 49
- 2.6. Range Reduction Factor, 50
- 2.7. Bistatic Radar Equation, 51
- 2.8. Radar Losses, 52
 - 2.8.1. Transmit and Receive Losses, 53
 - 2.8.2. Antenna Pattern Loss and Scan Loss, 53
 - 2.8.3. Atmospheric Loss, 53

- 2.8.4. Collapsing Loss, 53
- 2.8.5. Processing Loss, 55
- 2.9. Noise Figure, 57
- 2.10. Continuous Wave (CW) Radars, 63
 - 2.10.1. CW Radar Equation, 62
 - 2.10.2. Frequency Modulation, 64
 - 2.10.3. Linear Frequency Modulated CW Radar, 68
 - 2.10.4. Multiple Frequency CW Radar, 71
- 2.11. MATLAB Program "range_calc.m", 72
- Problems, 73
- Appendix 2-A: Chapter 2 MATLAB Code Listings, 78
 - Function "radar_eq.m" Listing, 78
 - Program "Fig2_1.m" Listing, 78
 - Function "lprf_req.m" Listing, 79
 - Program "Fig2_2.m" Listing, 80
 - Function "hprf_req.m" Listing, 80
 - Program "Fig2_3.m" Listing, 81
 - Function "power_aperture.m" Listing, 81
 - Program "Fig2_6.m" Listing, 82
 - Function "ssj_req.m" Listing, 83
 - Program "Fig2_7b.m" Listing, 84
 - Function "sir_req.m" Listing, 84
 - Program "Fig2_8.m" Listing, 85
 - Function "burn_thru.m" Listing, 85
 - Program "Fig2_9.m" Listing, 86
 - Function "soj_req.m" Listing, 86
 - Program "Fig2_10.m" Listing, 87
 - Function "range_clac.m" Listing, 88

PART II: Radar Signals and Signal Processing

Chapter 3: Linear Systems and Complex Signal Representation, 93

- 3.1. Signal Classifications, 93
- 3.2. The Fourier Transform, 94
- 3.3. Systems Classification, 95
 - 3.3.1. Linear and Nonlinear Systems, 95
 - 3.3.2. Time Invariant and Time Varying Systems, 95
 - 3.3.3. Stable and Nonstable Systems, 96
 - 3.3.4. Causal and Noncausal Systems, 96
- 3.4. Signal Representation Using the Fourier Series, 96
- 3.5. Convolution and Correlation Integrals, 98
 - 3.5.1. Energy and Power Spectrum Densities, 99
- 3.6. Bandpass Signals, 102
 - 3.6.1. The Analytic Signal (Pre-Envelope), 103
 - 3.6.2. Pre-Envelope and Complex Envelope of Bandpass Signals, 104
- 3.7. Spectra of a Few Common Radar Signals, 106
 - 3.7.1. Continuous Wave Signal, 106
 - 3.7.2. Finite Duration Pulse Signal, 107
 - 3.7.3. Periodic Pulse Signal, 108

- 3.7.4. Finite Duration Pulse Train Signal, 109
- 3.7.5. Linear Frequency Modulation (LFM) Signal, 111
- 3.8. Signal Bandwidth and Duration, 116
 - 3.8.1. Effective Bandwidth and Duration Calculation, 117
 - Single Pulse, 117
 - Finite Duration Pulse Train Signal, 118
 - LFM Signal, 119
- 3.9. Discrete Time Systems and Signals, 120
 - 3.9.1. Sampling Theorem, 121
 - Lowpass Sampling Theorem, 121
 - Bandpass Sampling Theorem, 123
 - 3.9.2. The Z-Transform, 124
 - 3.9.3. The Discrete Fourier Transform, 125
 - 3.9.4. Discrete Power Spectrum, 126
 - 3.9.5. Windowing Techniques, 127
 - 3.9.6. Decimation and Interpolation, 129
 - Decimation, 129
 - Interpolation, 132
- Problems, 133
- Appendix 3-A: Chapter 3 MATLAB Code Listings, 137
 - Program "Fig3_6.m" Listing, 137
 - Program "Fig3_8.m" Listing, 137
 - Program "Fig3_10.m" Listing, 139
- Appendix 3-B: Fourier Transform Pairs, 140
- Appendix 3-C: Z-Transform Pairs, 141

Chapter 4: The Matched Filter Radar Receiver, 143

- 4.1. The Matched Filter SNR, 143
 - 4.1.1. White Noise Case, 145
 - 4.2.2. The Replica, 147
- 4.2. General Formula for the Output of the Matched Filter, 147
 - 4.2.1. Stationary Target Case, 148
 - 4.2.2. Moving Target Case, 149
- 4.3. Waveform Resolution and Ambiguity, 151
 - 4.3.1. Range Resolution, 151
 - 4.3.2. Doppler Resolution, 153
- 4.4. Range and Doppler Uncertainty, 155
 - 4.4.1. Range Uncertainty, 155
 - 4.4.2. Doppler Uncertainty, 158
 - 4.4.3. Range-Doppler Coupling, 159
 - Range Error Estimate, 159
 - Doppler Error Estimate, 161
 - 4.4.4. Range-Doppler Coupling in LFM Signals, 162
- 4.5. Target Parameter Estimation, 163
 - 4.5.1. What Is an Estimator?, 163
 - 4.5.2. Amplitude Estimation, 164
 - 4.5.3. Phase Estimation, 165
- Problems, 165

Chapter 5: Ambiguity Function - Analog Waveforms, 169

- 5.1. Introduction, 169
- 5.2. Examples of the Ambiguity Function, 170
 - 5.2.1. Single Pulse Ambiguity Function, 170
 - 5.2.2. LFM Ambiguity Function, 173
 - 5.2.3. Coherent Pulse Train Ambiguity Function, 177
 - 5.2.4. Pulse Train Ambiguity Function with LFM, 181
- 5.3. Stepped Frequency Waveforms, 184
- 5.4. Nonlinear FM, 186
 - 5.4.1. The Concept of Stationary Phase, 187
 - 5.4.2. Frequency Modulated Waveform Spectrum Shaping, 191
- 5.5. Ambiguity Diagram Contours, 193
- 5.6. Interpretation of Range-Doppler Coupling in LFM Signals, 194
- Problems, 195
- Appendix 5-A: Chapter 5 MATLAB Code Listings, 197
 - Function "single_pulse_ambg.m" Listing, 197
 - Program "Fig5_2.m" Listing, 197
 - Program "Fig5_4.m" Listing, 197
 - Function "lfm_ambg.m" Listing, 198
 - Program "Fig5_5.m" Listing, 198
 - Program "Fig5_6.m" Listing, 199
 - Function "train_ambg.m" Listing, 199
 - Program "Fig5_8.m" Listing, 200
 - Program "Fig5_9.m" Listing, 200
 - Function "lfm_ambg_lfm.m" Listing, 201
 - Program "Fig5_10.m" Listing, 202
 - Program "Fig5_15.m" Listing, 202

Chapter 6: Ambiguity Function - Discrete Coded Waveforms, 203

- 6.1. Discrete Code Signal Representation, 203
- 6.2. Pulse Train Codes, 204
- 6.3. Phase Coding, 209
 - 6.3.1. Binary Phase Codes, 209
 - Barker Code, 210
 - Pseudo-Random Number (PRN) Codes, 218
 - Linear Shift Register Generators, 219
 - Maximal Length Sequence Characteristic Polynomial, 221
 - 6.3.2. Polyphase Codes, 225
 - Frank Codes, 225
- 6.4. Frequency Codes, 228
 - 6.4.1. Costas Codes, 228
- 6.5. Ambiguity Plots for Discrete Coded Waveforms, 230
- Problems, 231
- Appendix 6-A: Chapter 6 MATLAB Code Listings, 232
 - Program "Fig6_2.m" Listing, 232
 - Function "plot_figures_chapter6.m" Listing, 232
 - Program "Fig6_3.m" Listing, 233
 - Program "Fig6_8_10.m" Listing, 233

- Program "Fig6_15_16.m" Listing, 234
- Program "Fig6_17.m" Listing, 235
- Function "ambiguity_code.m" Listing, 235

Chapter 7: Pulse Compression, 237

- 7.1. Time-Bandwidth Product, 237
- 7.2. Radar Equation with Pulse Compression, 238
- 7.3. Basic Principle of Pulse Compression, 239
- 7.4. Correlation Processor, 241
- 7.5. Stretch Processor, 247
 - 7.5.1. Single LFM Pulse, 247
 - 7.5.2. Stepped Frequency Waveforms, 254
 - Range Resolution and Range Ambiguity in SFW, 256
 - 7.5.3. Effect of Target Velocity, 261
- Problems, 263
- Appendix 7-A: Chapter 7 MATLAB Code Listings, 265
 - Program "Fig7_3.m" Listing, 265
 - Function "matched_filter.m" Listing, 265
 - Function "power_integer_2.m" Listing, 267
 - Function "stretch.m" Listing, 267
 - Function "SWF.m" Listing, 269
 - Program "Fig7_20.m" Listing, 270

PART III: Special Radar Considerations**Chapter 8: Radar Wave Propagation, 275**

- 8.1. The Earth Impact on the Radar Equation, 275
- 8.2. Earth's Atmosphere, 275
- 8.3. Atmospheric Models, 277
 - 8.3.1. Index of Refraction in the Troposphere, 279
 - 8.3.2. Index of refraction in the Ionosphere, 280
 - 8.3.3. Mathematical Model for Computing Refraction, 281
 - 8.3.4. Stratified Atmospheric Refraction Model, 283
- 8.4. Four-Third Earth Model, 287
 - 8.4.1. Target Height Equation, 287
- 8.5. Ground Reflection, 289
 - 8.5.1. Smooth Surface Reflection Coefficient, 289
 - 8.5.2. Divergence, 293
 - 8.5.3. Rough Surface Reflection, 295
 - 8.5.4. Total Reflection Coefficient, 296
- 8.6. The Pattern Propagation Factor, 296
 - 8.6.1. Flat Earth, 299
 - 8.6.2. Spherical Earth, 301
 - 8.6.3. MATLAB Program "multipath.m," 303
- 8.7. Diffraction, 303
- 8.8. Atmospheric Attenuation, 310
 - 8.8.1. Atmospheric Absorption, 310

- 8.8.2. Atmospheric Attenuation Plots, 312
- 8.9. Attenuation Due to Precipitation, 317
- Problems, 318
- Appendix 8-A: Chapter 8 MATLAB Code Listings, 320
 - Function "refraction.m" Listing, 320
 - Program "Fig8_7.m" Listing, 321
 - Function "ref_coef.m" Listing, 321
 - Program "Fig8_11_12.m" Listing, 322
 - Program "Fig8_13_14.m" Listing, 322
 - Function "divergence.m" Listing, 323
 - Function "surf_rough.m" Listing, 323
 - Program "Fig8_17.m" Listing, 324
 - Function "multipath.m" Listing, 324
 - Function "airy01.m" Listing, 326
 - Program "Fig8_29.m" Listing, 327
 - Program "Fig8_30.m" Listing, 327
 - Function "atmo_absorp.m" Listing, 329
 - Program "Fig8_31.m" Listing, 330
 - Function "absorption_range.m" Listing, 330
 - Program "Fig8_33.m" Listing, 331
 - Function "atmospheric_attn.m" Listing, 332
 - Program "Fig8_34_35.m" Listing, 332
 - Program "Fig8_36.m" Listing, 333
 - Program "Fig8_37.m" Listing, 334

Chapter 9: Radar Clutter, 335

- 9.1. Clutter Definition, 335
- 9.2. Surface Clutter, 335
 - 9.2.1. Radar Equation for Area Clutter - Airborne Radar, 337
- 9.3. Volume Clutter, 339
 - 9.3.1. Radar Equation for Volume Clutter, 341
- 9.4. Surface Clutter RCS, 342
 - 9.4.1. Single Pulse Low PRF Case, 342
 - 9.4.2. High PRF Case, 348
- 9.5. Clutter Components, 349
- 9.6. Clutter Backscatter Coefficient Statistical Models, 351
 - 9.6.1. Surface Clutter Case, 352
 - 9.6.2. Volume Clutter Case, 353
- Problems, 355
- Appendix 9-A: Chapter 9 MATLAB Code Listings, 356
 - Function "clutter_rcs.m" Listing, 356
 - Program "Fig9_9_10.m" Listing, 357
 - Program "Fig9_12_13.m" Listing, 358
 - Program "Fig9_14.m" Listing, 359

Chapter 10: Moving Target Indicator (MTI) and Pulse Doppler Radars, 361

- 10.1. Clutter Power Spectrum Density, 361

- 10.2. Concept of a Moving Target Indicator (MTI), 362
 - 10.2.1. Single Delay Line Canceler, 363
 - 10.2.2. Double Delay Line Canceler, 364
 - 10.2.3. Delay Lines with Feedback (Recursive Filters), 367
- 10.3. PRF Staggering, 368
- 10.4. MTI Improvement Factor, 371
 - 10.4.1. Two-Pulse MTI Case, 372
 - 10.4.2. The General Case, 374
- 10.5. Subclutter Visibility (SCV), 375
- 10.6. Delay Line Cancelers with Optimal Weights, 375
- 10.7. Pulse Doppler Radars, 377
 - 10.7.1. Pulse Doppler Radar Signal Processing, 381
 - 10.7.2. Resolving Range Ambiguities, 381
 - 10.7.3. Resolving Doppler Ambiguities, 383
- 10.8. Phase Noise, 387
- Problems, 393
- Appendix 10-A: Chapter 10 MATLAB Code Listings, 395
 - Function "single_canceler.m" Listing, 395
 - Function "double_canceler.m" Listing, 395
 - Program "Fig10_8.m" Listing, 396
 - Program "Fig10_9.m" Listing, 396
 - Program "Fig10_10.m" Listing, 397
 - Program "Fig10_24.m" Listing, 398
 - Program "Fig10_25.m" Listing, 398
 - Program "Fig10_26.m" Listing, 398

PART IV: Radar Detection

Chapter 11: Random Variables and Random Processes, 403

- 11.1. Random Variables, 403
- 11.2. Multivariate Gaussian Random Vector, 406
 - 11.2.1. Complex Multivariate Gaussian Random Vector, 408
- 11.3. Rayleigh Random Variables, 409
- 11.4. The Chi-Square Random Variables, 410
 - 11.4.1. Central Chi-Square Random Variable with N Degrees of Freedom, 410
 - 11.4.2. Non-central Chi-Square Random Variable with N Degrees of Freedom, 411
- 11.5. Random Processes, 411
- 11.6. The Gaussian Random Process, 413
 - 11.6.1. Lowpass Gaussian Random Processes, 413
 - 11.6.2. Bandpass Gaussian Random Processes, 414
 - 11.6.3. The Envelope of a Bandpass Gaussian Process, 415
- Problems, 416

Chapter 12: Single Pulse Detection, 419

- 12.1. Single Pulse with Known Parameters, 419
- 12.2. Single Pulse with Known Amplitude and Unknown Phase, 422

- 12.2.1. Probability of False Alarm, 426
- 12.2.2. Probability of Detection, 427
- Problems, 430
- Appendix 12-A: Chapter 12 MATLAB Code Listings, 431
 - Function "que_func.m" Listing, 431
 - Function "marcumsg.m" Listing, 431
 - Program "Fig12_5.m" Listing, 432

Chapter 13: Detection of Fluctuating Targets, 433

- 13.1. Introduction, 433
- 13.2. Pulse Integration, 433
 - 13.2.1. Coherent Integration, 434
 - 13.2.2. Noncoherent Integration, 435
 - 13.2.3. Improvement Factor and Integration Loss, 436
- 13.3. Target Fluctuation: The Chi-Square Family of Targets, 438
- 13.4. Probability of False Alarm Formulation for a Square Law Detector, 439
 - 13.4.1. Square Law Detection, 441
- 13.5. Probability of Detection Calculation, 443
 - 13.5.1. Detection of Swerling 0 (Swerling V) Targets, 443
 - 13.5.2. Detection of Swerling I Targets, 445
 - 13.5.3. Detection of Swerling II Targets, 445
 - 13.5.4. Detection of Swerling III Targets, 448
 - 13.5.5. Detection of Swerling IV Targets, 450
- 13.6. Computation of the Fluctuation Loss, 451
- 13.7. Cumulative Probability of Detection, 453
- 13.8. Constant False Alarm Rate (CFAR), 456
 - 13.8.1. Cell Averaging CFAR (Single Pulse), 456
 - 13.8.2. Cell Averaging CAFR with Noncoherent Integration, 458
- 13.9. M-out-of-N Detection, 459
- 13.10. The Radar Equation Revisited, 460
- Problems, 462
- Appendix 13-A: The Incomplete Gamma Function, 465
 - The Gamma Function, 465
 - The Incomplete Gamma Function, 465
- Appendix 13-B: Chapter 13 MATLAB Code Listings, 467
 - Function "improv_fac.m" Listing, 467
 - Program "Fig13_2.m" Listing, 467
 - Function "threshold.m" Listing, 468
 - Program "Fig13_4.m" Listing, 468
 - Function "pd_swerling5.m" Listing, 469
 - Program "Fig13_5.m" Listing, 470
 - Function "pd_swerling1.m" Listing, 470
 - Program "Fig13_6.m" Listing, 471
 - Program "Fig13_7.m" Listing, 471
 - Function "pd_swerling2.m" Listing, 472
 - Program "Fig13_8.m" Listing, 473
 - Program "Fig13_9.m" Listing, 473
 - Function "pd_swerling3.m" Listing, 474

- Program "Fig13_10.m" Listing, 474
- Program "Fig13_11.m" Listing, 475
- Function "pd_swerling4.m" Listing, 475
- Program "Fig13_12.m" Listing, 477
- Function "fluct_loss.m" Listing, 477
- Program "Fig13_13.m" Listing, 479
- Program "Fig13A_1.m" Listing, 479

PART V: Radar Special Topics

Chapter 14: Radar Cross Section (RCS), 485

- 14.1. RCS Definition, 485
- 14.2. RCS Dependency on Aspect Angle and Frequency, 487
- 14.3. RCS Dependency on Polarization, 490
 - 14.3.1. Normalized Electric Field, 490
 - 14.3.2. Polarization, 490
 - 14.3.3. Target Scattering Matrix, 493
- 14.4. RCS of Simple Objects, 494
 - 14.4.1. Sphere, 495
 - 14.4.2. Ellipsoid, 497
 - 14.4.3. Circular Flat Plate, 500
 - 14.4.4. Truncated Cone (Frustum), 501
 - 14.4.5. Cylinder, 505
 - 14.4.6. Rectangular Flat Plate, 507
 - 14.4.7. Triangular Flat Plate, 510
- 14.5. RCS of Complex Objects, 512
- 14.6. RCS Prediction Methods, 513
 - 14.6.1. Computational Electromagnetics, 514
 - 14.6.2. Finite Difference Time Domain Method, 514
 - 14.6.3. Finite Element Method, 518
 - 14.6.4. Integral Equations, 518
 - 14.6.5. Geometrical Optics, 519
 - 14.6.6. Physical Optics, 520
 - Rectangular Plate, 520
 - N-Sided Polygon, 521
 - 14.6.7. Edge Diffraction, 522
- 14.7. Multiple Bounce, 522
- Problems, 523
- Appendix 14-A: Chapter 14 MATLAB Code Listings, 525
 - Function "rcs_aspect.m" Listing, 525
 - Program "Fig14_3.m" Listing, 525
 - Function "rcs_frequency.m" Listing, 526
 - Program "Fig14_5_6.m" Listing, 526
 - Program "Fig14_10.m" Listing, 527
 - Function "rcs_ellipsoid.m" Listing, 528
 - Program "Fig14_112a.m" Listing, 528
 - Function "rcs_circ_plate.m" Listing, 529
 - Function "rcs_frustum.m" Listing, 530
 - Function "rcs_cylinder.m" Listing, 531

- Program "Fig14_19.m" Listing, 532
- Function "res_rect_plate.m" Listing, 533
- Function "res_isosceles.m" Listing, 534
- Function "res_cylinder_cmplx.m" Listing, 535
- Program "fddd.m" Listing, 536
- Program "rectplate.m" Listing, 538
- Program "polygon.m" Listing, 539

Chapter 15: Phased Array Antennas, 541

- 15.1. Directivity, Power Gain, and Effective Aperture, 541
- 15.2. Near and Far Fields, 542
- 15.3. General Arrays, 543
- 15.4. Linear Arrays, 546
 - 15.4.1. Array Tapering, 549
 - 15.4.2. Computation of the Radiation Pattern via the DFT, 551
- 15.5. Planar Arrays, 559
 - 15.5.1. Rectangular Grid Arrays, 560
 - 15.5.2. Circular Grid Arrays, 562
 - 15.5.3. Concentric Grid Circular Arrays, 569
 - 15.5.4. Rectangular Grid with Circular Boundary Arrays, 570
 - 15.5.5. Hexagonal Grid Arrays, 570
- 15.6. Array Scan Loss, 586
- 15.7. Multiple Input Multiple Output (MIMO) - Linear Array, 588
- Problems, 591
- Appendix 15-A: Chapter 15 MATLAB Code Listings, 593
 - Program "Fig15_5.m" Listing, 593
 - Program "Fig15_7.m" Listing, 594
 - Function "linear_array.m" Listing, 594
 - Function "circular_array.m" Listing, 596
 - Function "rect_array.m" Listing, 598
 - Function "circ_array.m" Listing, 601
 - Function "rect_to_circ.m" Listing, 604
 - Program "Fig15_50.m" Listing, 605

Chapter 16: Adaptive Signal Processing, 607

- 16.1. Nonadaptive Beamforming, 607
- 16.2. Adaptive Signal Processing Using Least Mean Square (LMS), 611
- 16.3. The LMS Adaptive Array Processing, 615
- 16.4. Sidelobe Cancelers (SLC), 623
- 16.5. Space Time Adaptive Processing (STAP), 624
 - 16.5.1. Space Time Processing, 624
 - 16.5.2. Space Time Adaptive Processing, 627
- Problems, 631
- Appendix 16-A: Chapter 16 MATLAB Code Listings, 632
 - Function "LMS.m" Listing, 632
 - Program "Fig16_4_5.m" Listing, 632
 - Function "adaptive_array_lms.m" Listing, 633

- Function "la_sampled_wave.m" Listing, 634
- Function "Linear_array_FFT.m" Listing, 634
- Program "run_stap.m" Listing, 635
- Function "stap_std.m" Listing, 635
- Function "stap_smaa.m" Listing, 637
- Function "st_steering_vector.m" Listing, 638
- Function "smaa_st_steering_vector.m" Listing, 638

Chapter 17: Target Tracking, 639

Single Target Tracking

- 17.1. Angle Tracking, 639
 - 17.1.1. Sequential Lobing, 640
 - 17.1.2. Conical Scan, 641
- 17.2. Amplitude Comparison Monopulse, 644
- 17.3. Phase Comparison Monopulse, 647
- 17.4. Range Tracking, 653

Multiple Target Tracking

- 17.5. Track-While-Scan (TWS), 655
- 17.6. State Variable Representation of an LTI System, 656
- 17.7. The LTI System of Interest, 660
- 17.8. Fixed-Gain Tracking Filters, 661
 - 17.8.1. The $\alpha\beta$ Filter, 664
 - 17.8.2. The $\alpha\beta\gamma$ Filter, 667
- 17.9. The Kalman Filter, 677
 - 17.9.1. The Singer $\alpha\beta\gamma$ -Kalman Filter, 679
 - 17.9.2. Relationship between Kalman and $\alpha\beta\gamma$ Filters, 681
- 17.10. MATLAB Kalman Filter Simulation, 685
- Problems, 693

Appendix 17-A: Chapter 17 MATLAB Code Listings, 695

- Function "mono_pulse.m" Listing, 695
- Function "ghk_tracker.m" Listing, 695
- Function "ghk_tracker1.m" Listing, 696
- Program "Fig17_20s.m" Listing, 697
- Function "kalman_filter.m" Listing, 697
- Program "Fig17_29.m" Listing, 698
- Program "Fig17_30.m" Listing, 699
- Function "maketraj.m" Listing, 699
- Function "addnoise.m" Listing, 700
- Function "kalfilt.m" Listing, 701

Chapter 18: Tactical Synthetic Aperture Radars, 703

- 18.1. Introduction, 703
 - 18.1.1. Side Looking SAR Geometry, 704
- 18.2. SAR Design Considerations, 706
- 18.3. SAR Radar Equation, 711
- 18.4. SAR Signal Processing, 712

- 18.5. Side Looking SAR Doppler Processing, 713
- 18.6. SAR Imaging Using Doppler Processing, 717
- 18.7. Range Walk, 717
- 18.8. A Three-Dimensional SAR Imaging Technique, 717
 - 18.8.1. Background, 719
 - 18.8.2. DFTSQM Operation and Signal Processing, 719
 - Linear Arrays, 719
 - Rectangular Arrays, 721
 - 18.8.3. Geometry for DFTSQM SAR Imaging, 722
 - 18.8.4. Slant Range Equation, 724
 - 18.8.5. Signal Synthesis, 726
 - 18.8.6. Electronic Processing, 727
 - 18.8.7. Derivation of Eq. (18.71), 728
 - 18.8.8. Non-Zero Taylor Series Coefficient for the k^{th} Range Cell, 730
- Problems, 732
- Appendix 18-A: Chapter 18 MATLAB Code Listings, 733
 - Program “*Fig18_12_13.m*” Listings, 733

Bibliography, 735

Index, 743