

CONTENTS

PREFACE	v
CHAPTER 1. FUNDAMENTAL PRINCIPLES	1
Introductory Remarks, 1. Coordinate Systems, 1. Linear Velocity and Acceleration, 3. Angular Velocity and Acceleration, 5.	
Elements of Vector Analysis	
Vectors and Scalars, 5. Composition of Displacements; Parallelogram Law of Addition, 6. Multiplication of a Vector by a Scalar, 8. Derivative of a Vector with Respect to a Single Scalar Variable, 9. Moving Reference Systems, 10. Components of a Vector in Terms of Unit Coordinate Vectors, 14. Transformation of Vector Components from One Set of Cartesian Axes to Another, 15. Scalar, or Dot, Product of Two Vectors, 18. Vector, or Cross, Product of Vectors, 19. The Gradient Vector, 21. Scalar and Vector Fields; the Line Integral of a Vector, 22.	
The Laws of Motion	
The Development of Dynamics, 23. Principle of Inertia; Newton's First Law, 24. Newton's Second Law; the Equation of Motion, 24. Newton's Third Law of Motion, 25. Inertial Systems and the Validity of Newton's Laws, 28. Fundamental Dimensions; the Dimensional Consistency of Equations, 30. Problems, 31.]	
CHAPTER 2. STATICS OF A PARTICLE	34
Equilibrium of Forces, 34. Polygon of Forces; Triangle of Forces, 35. The Flexible String, 36. The Rigid Body; Transmissibility of Force, 38. Smooth Constraining Surfaces, 39. Rough Constraining Surfaces; Static Friction, 41. String in Contact with a Rough Curved Surface, 45. Problems, 47.	
CHAPTER 3. STATICS OF RIGID BODIES	50
Introduction, 50.	
Mass Centers	
Center of Mass of a System of Particles, 50. Mass Centers of Solid Bodies, 53. Center of Mass of a Body Containing a Cavity, 55. Use of Arbitrary Coordinates, 57.	
Equilibrium of Rigid Bodies	
Extent of a System; Internal and External Forces, 57. Moment of a Force, 58. General Conditions of Equilibrium for a Rigid Body Acted upon by a System of Coplanar Forces, 59. Composition of Parallel Forces, 60. Center of Gravity of a System of Particles, 61. Miscellaneous Examples, 62. Reactions at Smooth Joints, 64. The Couple, 66. Reduction of an Arbitrary System of Forces to a Single Force Plus a Couple, 67. Reactions at Rigid Joints, 67. Problems, 69.	

CHAPTER 4. STATICS OF THE SUSPENDED STRING OR CABLE . . . 73

Introduction, 73. Light Cable Supporting a Horizontal Roadway; the Suspension Bridge, 73. Uniform Cable Supporting Its Own Weight; the Uniform Catenary, 75. Points of Support Not at the Same Level, 77. Determination of the Parameter a of the Catenary, 79. Approximate Determination of the Parameter a for a Tightly Stretched String, 80. Parabolic Catenary, 81. Catenary of Uniform Strength, 81. Heavy String or Cable Subject to Smooth Constraint, 83. Problems, 84.

CHAPTER 5. WORK AND THE STABILITY OF EQUILIBRIUM . . . 86

Work and Potential Energy
 Work Done by a Force, 86. Potential Energy and the Conservative Field, 87. Work Required to Raise a System of Particles at the Earth's Surface; the Uniform Field, 89. Conservation of Energy; Kinetic Energy, 90. Work Required to Stretch an Elastic String, 91.
 The Law of Gravitation
 Origin and Statement of the Law; Gravitational Field Strength, 92. Potential Energy in a Gravitational Field; Potential, 93. Field and Potential of an Extended Body, 93. Field and Potential of a Homogeneous Spherical Body, 95. Principle of Virtual Work
 Applied Forces and Forces of Constraint; Virtual Displacements, 97. Equilibrium and Finite Displacements; the Pulleys of Stevinus and the Inclined Plane of Galileo, 98. Infinitesimal Virtual Displacements; Statement of the Principle of Virtual Work, 100. Work Done by Internal Forces, 102. Miscellaneous Examples, 104.
 Stability of Equilibrium
 Equilibrium of Conservative Forces, 107. Potential Energy a Function of a Single Scalar Variable, 108. Problems, 112.

CHAPTER 6. MOTION OF A PARTICLE IN A UNIFORM FIELD . . . 116

One-dimensional Motion of a Particle Acted upon by a Constant Force
 Falling Body, 116. Particle on a Smooth Inclined Plane, 118. Atwood's Machine, 118. Kinetic Friction, 120.
 Flight of a Projectile
 Projectile in a Vacuum; Equation of the Path, 124. Miscellaneous Examples, 125. Falling Body; Resistance Proportional to the First Power of the Velocity, 128. Resistance Proportional to the Second Power of Velocity, 129. Projectile with Air Resistance, 130. Problems, 132.

CHAPTER 7. OSCILLATORY MOTION OF A PARTICLE IN ONE DIMENSION . . . 153

Motion of a Simple Pendulum; the Oscillator Equation, 135. Physical Interpretation of Terms, 137. Exponential Method of Solution, 138. Energy of the Oscillator, 138.
 The Damped Harmonic Oscillator
 The General Solution; the Underdamped Case, 139. Critically Damped and Overdamped Cases, 142.
 The Forced Harmonic Oscillator
 General Solution, 144. Resonance, 146. Rate at Which Work Is Being Done, 149. Application to an Elastically Bound Electron, 151.

Departures from Harmonic Oscillations

Natural Period of the Undamped System, 152. Forced Motion of an Undamped Nonlinear System, 153. Thermal Expansion of a Crystal, 155. Problems, 157.

CHAPTER 8. MOTION OF A SYSTEM OF PARTICLES 160

Linear and Angular Momentum for a Single Particle, 160.

System of Particles

Linear Momentum of the Center of Mass of a System, 162. Angular Momentum of a System of Particles, 164. Torque Equation with Reference to an Arbitrary Origin, 165. Kinetic Energy of a System of Particles, 168. Angular Momentum of a System of Particles in Terms of the Center of Mass, 170. Relative Motion of Two Bodies; the Reduced Mass, 171.

Impulsive Forces and Impact

Nature of an Impulse, 173. Impact, Elastic and Inelastic; Coefficient of Restitution, 175. Motion Relative to the Center of Mass, Loss of Energy during Impact, 179. Generalization of Newton's Rule; Oblique Impact of Two Smooth Spheres, 180. Comparison of the Rest and Center-of-mass Systems of Coordinates for the Oblique Impact of Two Particles, 182.

Motion of a Body When the Mass Varies

Finding the Correct Equation of Motion When the Mass Varies, 184. Motion of a Rocket-propelled Body, 186. Problems, 187.

CHAPTERS. MOTION OF A RIGID BODY IN A PLANE 192

Specification of a Rigid Body, 192. General Displacement of a Rigid Body 193. Space and Body Centroids for Velocity; Point of Instantaneous Rest, 194. Infinitesimal Rotations and the Angular-velocity Vector, 197.

Dynamics of a Rigid Body in a Plane

Kinetic Energy of Rotation; the Moment of Inertia, 199. Angular Momentum of a Rigid Body Moving Parallel to a Fixed Plane; the Rotational Equation of Motion, 200. Theorem of Parallel Axes, 201. Calculation of Moments of Inertia, 262. Coordinate Systems for Rigid Bodies, 203. The Compound Pendulum, 205. Use of the Instantaneous Axis, 207. Rolling and Sliding Motion of a Sphere, 209.

Impulsive Motion of a Rigid Body in a Plane

Impulsive Torque, 211. Center of Percussion, 212. Newton's Rule for the Smooth Impact of Two Extended Bodies, 213. Connected Systems, 216. Problems, 217.

CHAPTER 10. MOTION OF A PARTICLE UNDER THE ACTION OF A CENTRAL FORCE 223

Kinetic Energy in Plane Polar Coordinates, 223. Acceleration in Plane Polar Coordinates, 224. Areal Velocity and Angular Momentum of a Particle Moving in a Central Field, 225.

Inverse-square Field : The Orbit

Integration of the Equations of Motion, 227. Equation of the Orbit by the Energy Method, 230. Energy and Classification of the Orbits, 232.

Kepler's Laws

Statement of Kepler's Laws, 234. Derivation of the Law of Force from Kepler's Laws, 236. The Two-body Problem and Kepler's Third Law, 236.

Disturbed Circular Orbits

Stability of Circular Orbits, 237.

Apsides

Apsidal Distances and Apsidal Angles, 240. Apsides in a Nearly Circular Orbit; Advance of the Perihelion, 242. Problems, 244.

CHAPTER 11. ACCELERATED REFERENCE SYSTEMS AND CONSTRAINED MOTION OF A PARTICLE. 248

Motion of a Particle in an Accelerated Reference System

Nature of the Problem, 248. Calculation of the Inertial Reaction in a Moving Frame, 249. Application of the Principles, 252. The Foucault Pendulum, 255.

Motion of a Particle along a **Surface or a Curve**

Introductory Examples, 257. Motion along a Smooth Plane Curve; Normal and Tangential Accelerations, 259. More General Treatment of Integrable Constraints; Motion Confined to a Smooth Surface of Arbitrary Form, 261. Equation of Energy, 262. The Angular-momentum Integral, 263. Rough Constraints; Particle Sliding on a Rough Wire, 266. The Pendulum of Arbitrary Amplitude, 267. Problems, 269.

CHAPTER 12. MOTION OF A RIGID BODY IN THREE DIMENSIONS 272

The Instantaneous Axis, 272. Angular Momentum in Term8 of Its Components; Moment8 and Product8 of Inertia, 273. Principal Axes, 275. Determination of the Other Two Principal Axes When One is Given, 278. Centrifugal Reactions; Dynamically Balanced Body, 280. Moment of Inertia about an Arbitrary Axis; Ellipsoid of Inertia, 282. Rotational Kinetic Energy of a Rigid Body, 285. Description of the Free Rotation of a Rigid Body in Term8 of the Ellipsoid of Inertia, 287. Classes of Problems to Be Considered in Rigid Dynamics, 289. Motion of a Rigid Body Referred to Rotating Axes; Euler's Dynamical Equations, 290. Constancy of Energy and Angular Momentum by Means of Euler's Equations, 291. Free Rotation of the Earth, 292. Free Motion of a Rigid Body Referred to Axes Having a Fixed Direction in Space; Motion of the Earth, 296.

Motion of a Top

Choice of Coordinates; Equation8 of Motion, 302. Energy and Angular-momentum Integrals, 305. Limits of the θ Motion, 307. Precession with Nutation, 309. Precession without Nutation, 309. The Sleeping Top, 312. **Gyroscopic** Action; the Rising Top, 313. Problems, 314.

CHAPTER 13. GENERALIZED COORDINATES. 317

Holonomic and Nonholonomic Constraints; Degrees of Freedom, 317. Kinetic Energy in Curvilinear Coordinates, 319. Generalized Coordinates; Lagrange's Equations for a Single Particle, 322. Lagrange's Equations for a System of Particles, 330. Generalized Momentum, 331. Motion of a Symmetrical Top from Lagrange's Equations, 332. The Hamiltonian Function; Hamilton's Equations, 334. Problems, 339.

CHAPTER 14. VIBRATING SYSTEMS AND NORMAL COORDINATES 341

Coupled Pendulums, 342. Normal Coordinates, 344. Equations of Motion and the Energy in Term8 of Normal Coordinates, 345. Transfer of Energy from One Pendulum to the Other, 346. Possibility of Expressing an Arbitrary System in Terms of Normal Coordinates, 348. Dissipative Systems, 353. Forced Oscillations, 355. Vibration8 of Molecules, 357. Summary of Properties of Normal Coordinates, 358. Problems, 358.

CHAPTER 15. VIBRATING STRINGS AND WAVE MOTION . . .	362
Equations of Motion, 362. General Solution, 363. Determination of the Coefficients A_n and B_n , 365. Energy and Normal Coordinates of a Vibrating String, 367. Damped and Forced Motion of a Vibrating String, 370. Transverse Wave Motion in a String	
Traveling-wave Solution, 372. Terminal Conditions and Initial Conditions 375. More General Discussion of Effect of Initial Condition 378. Standing Waves, 380. Behavior at a Junction; Energy Flow, 381. Problems, 383.	
APPENDIX 1. AREA AND VOLUME ELEMENTS IN COMMON CO-ORDINATE SYSTEMS	385
Plane Polar Coordinates, 385. Spherical Polar Coordinates, 385. Cylindrical Polar Coordinates, 386.	
APPENDIX 2. ELEMENTS OF ORDINARY DIFFERENTIAL EQUATIONS	387
The Nature of Differential Equations, 387. The Nature of the Solution of a Differential Equation, 388. Formation of Differential Equation by Elimination of Constants, 389.	
Equations of the First Order	
Exact Equations, 389. Solution by Separation of Variables, 390. Integrating Factors, 390. The Linear Equation of the First Order, 391. Nonlinear First-order Equations, 392.	
Equations of the Second and Higher Orders	
Linear with Constant Coefficients; Right Side Equal to Zero, 293. The Case of Equal Roots, 394. The Operator D , 395. Linear Equations with Constant Coefficients; Right Side Not Equal to Zero, 397.	
Miscellaneous Method for Equations of Order Higher Than the First	
The Equation Does Not Contain y Explicitly, 399. The Equation Does Not Contain x Explicitly, 399. Procedure When One Integral Belonging to the Complementary Function Is Known, 400. Problems, 401.	
APPENDIX 3. NOTE ON HYPERBOLIC FUNCTIONS.	402
APPENDIX 4. COMMONLY EMPLOYED EXPRESSIONS INVOLVING PARTIAL DERIVATIVES	404
APPENDIX 5. NOTE ON FOURIER SERIES	406
Problems, 412	
INDEX.	413